Lecture 12: Neural networks STATS 202: Data Mining and Analysis

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## Announcements



- Homework 4 due this Friday.
- Final project predictions due this Sunday night.
- Final project writeup is due next Wednesday.

Optional (will take max of Final project & Final exam).
 Final exam is a week from this Saturday

- Time: August 19 @ 7:00 P.M. 10:00 P.M.
- Location: Skilling Auditorium
- Practice exam to be released Friday
- Accommodation requests should be made now
- No formal lectures next week
- Review this Friday



#### Introduction

- Logistic regression
- Back propagation
- Function approximation
- Feature extraction
- Model generalization
- Advanced topics

## Neural networks



Currently, the most popular algorithm amongst ML practitioners.

- Many times, used within the context of Artificial Intelligence.
- Simply a general function estimation algorithm.
- ▶ Though is often hyped up the media.



Gartner's hype cycle for 2018.



Lots of buzz words, but what do they mean?

### **Definitions**:

- ► Al: human-like machines or programs.
- ► *ML*: Algorithms that learn from data.
- DL: A type of ML algorithm, using neural networks (typically with many layers).











Some potential answers

► A universal function approximator.





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- ► A universal function approximator.
- ► A feature extractor.





Some potential answers

- ► A universal function approximator.
- ► A feature extractor.
- ► A model generalizer.



**Recall**: logistic regression is a linear model with a logit link function, i.e.

$$\mathbb{P}(Y=1|\mathbf{X}) = \sigma(\beta_0 + \beta_1 X_1 + \dots + \beta_p X_p) : \sigma(z) = \frac{1}{1 + exp(-z)}$$
(1)

Let's rephrase this by:

- 1. Using b to denote  $\beta_0$  (aka the bias)
- 2. Using **W** to denote  $(\beta_0, ..., \beta_p)$  (aka the weights)
- 3. Using matrix notation

$$\mathbb{P}(Y=1|\mathbf{X}) = \underbrace{\sigma}_{non-linearity} (\mathbf{X}\mathbf{W} + b)$$
(2)



When the function is non-linear, our prior option was to do feature transformations, e.g.

- Expand predictor set (e.g. non-linear transformations, interactions, etc.).
- Define a kernel (e.g. find a function f(·, ·) that is positive definite).



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**Another option**: build the non-linearity into the model specification, e.g.

$$\mathbb{P}(Y=1|\mathbf{X}) = \sigma(\sigma(\mathbf{X} \mathbf{W}_1 + b_1) \mathbf{W}_2 + b_2)$$
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This is a neural network (with 1 hidden layer)!



For logistic regression:

$$\mathbb{P}(Y=1|\mathbf{X}) = \sigma(\mathbf{X} \underbrace{\mathbf{W}}_{p \times 1} + \underbrace{b}_{1 \times 1})$$
(4)



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For neural networks:

$$\mathbb{P}(Y=1|\mathbf{X}) = \sigma(\sigma(\mathbf{X}\underbrace{\mathbf{W}_1}_{p \times M} + \underbrace{b_1}_{1 \times M})\underbrace{\mathbf{W}_2}_{M \times 1} + \underbrace{b_2}_{1 \times 1})$$
(5)

M specifies how many hidden nodes we have

- Called 'hidden' since it's not directly observed by us.
- Also referred to as 'embeddings'.

Hidden nodes





FIGURE 11.2. Schematic of a single hidden layer, feed-forward neural network.

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## Hidden layers



We can iteratively apply our non-linear operations, e.g.

$$\mathbb{P}(Y=1|\mathbf{X}) = \sigma(\cdots \sigma(\sigma(\mathbf{X} \mathbf{W}_1 + b_1)\mathbf{W}_2 + b_2)\cdots \mathbf{W}_B + b_B)$$
(7)

Where *B* is the number of iterations (i.e. *hidden layers*).

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(7)

Where *B* is the number of iterations (i.e. *hidden layers*).

Each activation (e.g. sigmoid) can approximate a local change

• B sigmoids  $\implies$  approximate at  $\approx$  B points



n.b. Each layer needs the number of hidden nodes specified.



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e.g. Which of digits 0 through 9 is this photo?

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Recall: for logistic regression, we're modeling

$$\log \left[ \frac{\mathbb{P}(Y=1|\mathbf{X})}{1-\mathbb{P}(Y=1|\mathbf{X})} \right] = \beta_0 + \beta_1 X_1 + \ldots + \beta_p X_p \quad (8)$$
$$= \mathbf{XW} \quad (9)$$

where **X** is our  $n \times p$  design matrix and **W** is our  $p \times 1$  parameter vector.



## Multinomial logistic regression



For multinomial regression, let  $Y \in \{1, \ldots, K\}$ . We can model

$$\log \left[ \frac{\mathbb{P}(Y=1|\mathbf{X})}{\mathbb{P}(Y=K|\mathbf{X})} \right] = \mathbf{X}\mathbf{W}_{1}$$
(10)

$$\operatorname{og}\left[\frac{\mathbb{P}(Y=2|\mathbf{X})}{\mathbb{P}(Y=K|\mathbf{X})}\right] = \mathbf{X}\mathbf{W}_{2}$$
(11)

$$= \cdots$$
 (12)

$$\log\left[\frac{\mathbb{P}(Y=K-1|\mathbf{X})}{\mathbb{P}(Y=K|\mathbf{X})}\right] = \mathbf{XW}_{\mathbf{K}-1}$$
(13)

. . .

where each  $\mathbf{W}_{\mathbf{k}}$  is a  $p \times 1$  parameter vector.

Exponentiating both sides and solving for  $\mathbb{P}(Y = K | \mathbf{X})$  (using the fact that the probabilities have to sum to 1) gives us

$$\mathbb{P}(Y = K | \mathbf{X}) = \frac{1}{1 + \sum_{k=1}^{K-1} e^{\mathbf{X}\mathbf{W}_k}}$$
(14)



#### Equivalently, can represent the multinomial logistic model as

$$\log \mathbb{P}(Y=1|\mathbf{X}) = \mathbf{X}\mathbf{W}_1 - \log(Z)$$
(15)

$$\log \mathbb{P}(Y=2|\mathbf{X}) = \mathbf{X}\mathbf{W}_2 - \log(Z)$$
(16)

$$\cdots = \cdots$$
 (17)

$$\log \mathbb{P}(Y = K | \mathbf{X}) = \mathbf{X} \mathbf{W}_{\mathbf{K}} - \log(Z)$$
(18)

resulting in the following probabilities

$$\mathbb{P}(Y=1|\mathbf{X}) = \frac{\exp(\mathbf{X}\mathbf{W}_1)}{\sum_{k=1}^{K}\exp(\mathbf{X}\mathbf{W}_k)}$$
(19)

$$\mathbb{P}(Y=2|\mathbf{X}) = \frac{\exp(\mathbf{X}\mathbf{W}_2)}{\sum_{k=1}^{K}\exp(\mathbf{X}\mathbf{W}_k)}$$
(20)

$$\cdots = \cdots \tag{21}$$

$$\mathbb{P}(Y = K | \mathbf{X}) = \frac{\exp(\mathbf{X}\mathbf{W}_{K})}{\sum_{k=1}^{K} \exp(\mathbf{X}\mathbf{W}_{k})}$$
(22)



This leads us to the softmax function, i.e.

softmax
$$(\mathbf{XW}_1, \dots, \mathbf{XW}_K)_k = \frac{e^{\mathbf{XW}_k}}{\sum_{l=1}^K e^{\mathbf{XW}_l}}$$
 (23)

Or, more succintly, we have

softmax
$$(\mathbf{XW}^{\mathbf{K}})_{k} = \frac{\exp((\mathbf{XW}^{\mathbf{K}})_{k.})}{\sum_{k=1}^{K} \exp((\mathbf{XW}^{\mathbf{K}})_{k.})}$$
 (24)

where the  $p\times K$  matrix  $W^K$  is simply the (concatenated) matrix of  $W_1,\ldots,W_K.$ 

This is what multiclass neural networks are modeling!

## The chain rule



Recall: In logistic regression we try to maximize the likelihood

Equivalent to minimizing the cross-entropy

$$L(y_{i}, f(\mathbf{X}_{i})) = -y_{i} \log(p_{i}) - (1 - y_{i}) \log(1 - p_{i}), \text{ where}(25)$$

$$p_{i} = \frac{1}{1 + exp(-Z_{i})}$$

$$Z_{i} = \mathbf{X}_{i} \mathbf{W}$$
(27)

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Can apply the derivative chain rule to get our gradient, i.e.

$$\frac{\partial L(y_i, f(\mathbf{X}_i))}{\partial \mathbf{W}} = \frac{\partial L(y_i, f(\mathbf{X}_i))}{\partial p_i} \times \frac{\partial p_i}{\partial Z_i} \times \frac{\partial Z_i}{\partial \mathbf{W}}$$
(28)

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(28)

Which gives us

$$\frac{\partial L(y_i, f(\mathbf{X}_i))}{\partial \mathbf{W}} = \mathbf{X}_i(y_i - p_i)$$
(29)



Neural networks are simply a generalization of the logistic regression case, e.g. for

$$\mathbb{P}(Y=1|\mathbf{X}) = \sigma(\sigma(\mathbf{X} \mathbf{W}_1) \mathbf{W}_2)$$
(30)



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$$\mathbb{P}(Y=1|\mathbf{X}) = \sigma(\sigma(\mathbf{X} \, \mathbf{W}_1) \, \mathbf{W}_2) \tag{30}$$

Our loss is

$$L(y_i, f(\mathbf{X}_i)) = -y_i \log(p_i) - (1 - y_i) \log(1 - p_i), \text{ where}(31)$$

$$p_i = \frac{1}{1 + \exp(-Z_{2,i})}$$
(32)

$$Z_{2,i} = h_i W_2 \tag{33}$$

$$h_i = \frac{1}{1 + exp(-Z_{1,i})}$$
(34)

$$Z_{1,i} = \mathbf{X} \mathbf{W}_1 \tag{35}$$

## Backpropagation



#### Our loss is

$$L(y_i, f(\mathbf{X}_i)) = -y_i \log(p_i) - (1 - y_i) \log(1 - p_i), \text{ where}(36)$$

$$p_i = \frac{1}{1 + exp(-Z_{2,i})}$$
 (37)

$$Z_{2,i} = h_i \boldsymbol{W}_2 \tag{38}$$

$$h_i = \frac{1}{1 + exp(-Z_{1,i})}$$
(39)

$$Z_{1,i} = \mathbf{X} \mathbf{W}_1 \tag{40}$$

#### Applying the derivative chain rule:

$$\frac{\partial L(y_i, f(\mathbf{X}_i))}{\partial \mathbf{W}_2} = \frac{\partial L(y_i, f(\mathbf{X}_i))}{\partial p_i} \times \frac{\partial p_i}{\partial Z_{2,i}} \times \frac{\partial Z_{2,i}}{\partial \mathbf{W}_2} \frac{\partial L(y_i, f(\mathbf{X}))}{\partial \mathbf{W}_1} = \frac{\partial L(y_i, f(\mathbf{X}))}{\partial p_i} \times \frac{\partial p_i}{\partial Z_{2,i}} \times \frac{\partial Z_{2,i}}{\partial h_i} \times \frac{\partial h_i}{\partial Z_{1,i}} \times \frac{\partial Z_{1,i}}{\partial \mathbf{W}_1}$$

## Gradient descent



Our gradient is estimated using our data, i.e.  $(y_i, \mathbf{X}_i) : i = 1, 2, ..., n.$ 



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We can estimate it using, e.g.

- Stochastic gradient descent: estimating our (full) gradient using just one observation.
- Gradient descent: estimating our (full) gradient using all observations.
- Mini-batch gradient descent: using a (random) subsample of our observations.

Each will trade off between variance for the gradient and memory size.



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When done iteratively, we'll typically specify a stopping point (e.g. by using a dev set).



The use of non-linearities results in multiple minima, tendency to overfit, and can be unstable. Some considerations to make:

- Set initial weight values near zero.
- Over parameterize and regularize heavily.
- Standardize input features.
- Use a dev set and stop training earlier.
- Try out different weight randomizations and take the one with the lowest (validated) error.
  - Or average the predictions (or apply bagging).

Estimating neural network parameters simply requires '*propagating back*' errors.

We're just applying (matrix) multiplications

GPU's can be very good for this

Matrix multiplications can get pretty big (for large networks)

Commonly not worth it to use the Hessian

- Should be careful with large values going into sigmoid activations
  - Results in saturated gradients



#### Hornik's theorem

Whenever the activation function is continuous, bounded, and non-constant, then, for arbitrary compact subsets  $X \subseteq \mathbb{R}^k$ , standard multilayer feedforward networks can approximate any continuous function on X arbitrarily well with respect to uniform distance, provided that sufficiently many hidden units are avaiable.



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Whenever the activation function is continuous, bounded, and non-constant, then, for arbitrary compact subsets  $X \subseteq \mathbb{R}^k$ , standard multilayer feedforward networks can approximate any continuous function on X arbitrarily well with respect to uniform distance, provided that sufficiently many hidden units are avaiable.

**In words**: A 2-layer neural network with enough hidden nodes can closely approximate any continuous function f(x).

References: Cybenko (1989) "Approximations by superpostions of sigmoidal function" Hornik (1991) "Approximation Capabilities of Multilayer Feedforward Networks" Leshno and Schocken (1993) "Multilayer Feedforward Networks with Non-Polynomial Activation Functions Can Approximate Any Function"

Given enough hidden nodes, we can approximate any function.



Check out this visual example of this.

Some caveats to the theorem

- We're approximating the function within some bound, i.e.  $|\hat{f}_n(x) f(x)| < \epsilon$ .
- ▶ Result is meant for *continuous* functions on *compact* subsets of ℝ.
- Nothing is guaranteed on the how quickly we can learn the function's parameters.
- Other function estimators also do a good job approximating!



For non-linear functions,

Logistic regression: expand our feature set via transformations

Neural network: define the model non-linearly



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Logistic regression: expand our feature set via transformations

• We have to specify the feature transformations

Neural network: define the model non-linearly

The model learns the feature transformations



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• We have to specify the feature transformations

Neural network: define the model non-linearly

- The model learns the feature transformations
- This helps us greatly when dealing with abstract or high dimensional problems (e.g. images & text)!

### Feature representation



## How do the feature transformations get learned? 0.5 0.5 0 -0.5 -0.5 -1 -0.5 0.5 Original representation of curves Hidden layer representation of curves

Well demonstrated by Chris Olah's blog.

## Example: The MNIST data





A linear model (e.g. for multinomial logistic regression)

## Example: The MNIST data





#### Neural network's learned (kernel) features.

## Model generalizations

A series

Knowing that we can simply back propagate errors via multiplication opens many doors for us, e.g.



#### Google's InceptionNet architecture

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A series

Knowing that we can simply back propagate errors via multiplication opens many doors for us, e.g.



Google's InceptionNet architecture

## **Problem**: large networks are vulnerable to vanishing/exploding gradients.

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Recall: Our gradient is simply a product of partial derivatives.

$$\frac{\partial C}{\partial b_1} = \sigma'(z_1) \times w_2 \times \sigma'(z_2) \times w_3 \times \sigma'(z_3) \times w_4 \times \sigma'(z_4) \times \frac{\partial C}{\partial a_4}$$

**Neural Network** 

Example neural network and gradient.



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Neural Network

Example neural network and gradient.

Question: What is the derivative of the sigmoid function?





Google's InceptionNet address this via strategically placed loss functions.



#### Google's InceptionNet architecture



We can also train models end to end, e.g.





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**Or**: in a modular fashion, e.g. pre-training.



#### Or over multiple tasks (i.e. multi-task learning), e.g.



Kendall et al. 2017's multi-task model

## Model generalizations



Many researchers will create unique architectures for specific problems, e.g. *Instacart* 



The prediction problem

## Model generalizations



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The prediction problem



#### The intial solution



Another example using the Netflix data.



Figure 5. A sample DNN architecture for learning movie embeddings from collaborative filtering data.



#### The skip gram model





## An *interactive demo* that allows you to play with a neural network.



## Additional topics

Neural net related core topics:

- Weight initializations
- Activation functions
- Optimization functions
- Loss functions
- Normalization
- Regularization / dropout
- Model architectures
- Hyperparameter optimization
- Bayesian neural networks
- Computation graphs
- Software / platforms
- Encoding / adding outside knowledge
- Hardware accelerators

Neural net applied topics:

- Computer vision
- Natural language processing
- Signal processing
- Generative models
- Unsupervised learning
- Reinforcement learning
- One/Zero shot learning
- Transfer learning
- Auto-ML
- Memory Augmented Neural Networks



## [1] ESL. Chapter 11

[2] Pancha N, Zhai A, Leskovec J, Rosenberg C. PinnerFormer: Sequence Modeling for User Representation at Pinterest. arXiv 2022.